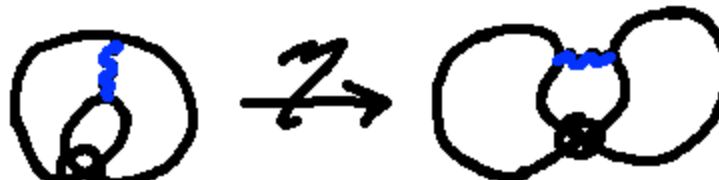


## Lecture #6

These are the handwritten notes for this lecture. We also used the slides in Lecture #5.

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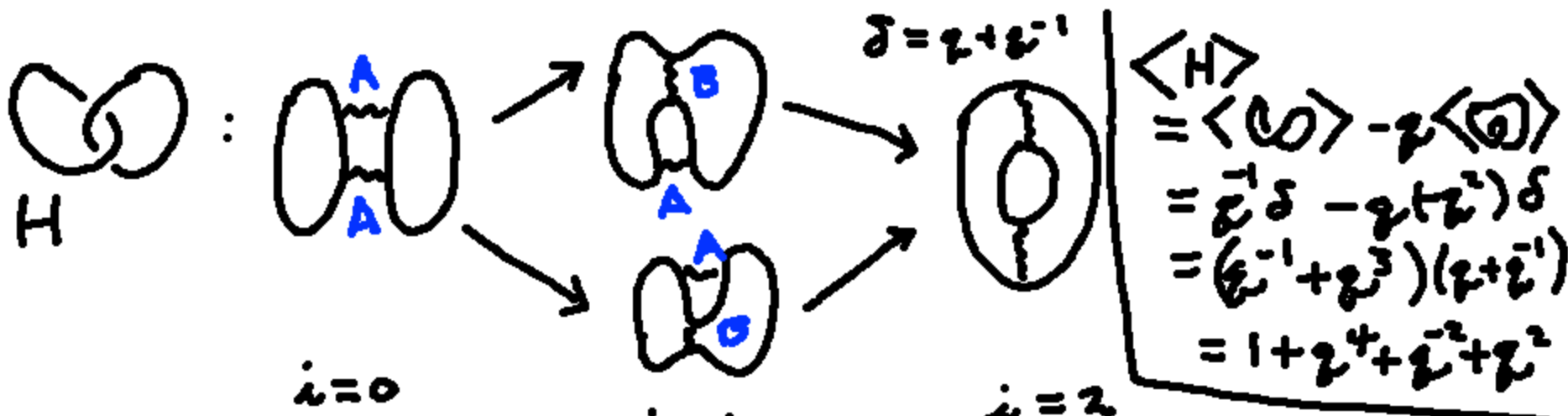
Note: 

A re-smoothing in virtual category can be from one loop to one loop.

Note: 

A re-smoothing in Knotoid category can be from one loop to one loop.

These facts mean that Khovanov Homology for virtuals and knotoids requires special attention.



$$\begin{aligned}
 \langle H \rangle &= \langle \text{torus} \rangle - 2 \langle \text{handle} \rangle \\
 &= z^{-1} \delta - 2(z^2) \delta \\
 &= (z^{-1} + z^3)(z + z^{-1}) \\
 &= 1 + z^4 + z^{-2} + z^2
 \end{aligned}$$

$$\langle H \rangle = \sum_i (-1)^i z^i$$

$i \setminus j$	-2	0	2	4
0	$x \otimes y$	$x \otimes 1$ $1 \otimes y$	$1 \otimes 1$	
1		$(x, 0)$ $(0, x)$	$(1, 0)$ $(0, 1)$	
2		$x \otimes y$	$x \otimes 1$ $1 \otimes y$	$1 \otimes 1$

$$\begin{aligned}
 &+ (z^{-2} + \cancel{z} + z^2) \\
 &- (\cancel{z} + \cancel{z} z^2) \\
 &+ (1 + \cancel{z} z^2 + z^4)
 \end{aligned}$$

$\partial(x \otimes y) = 0 + 0 = 0$   
 $\partial(x \otimes 1) = (x, 0) - (0, y) = (x, -y)$   
 $\partial(1 \otimes y) = (x, 0) - (0, x) = (x, -x)$   
 ... do this homology as an exercise!

Other examples



8 states  
 + more enhanced states



min  
 16 states  
 + more enhanced states

Knotoids



ends not  
 necess in  
 same region.

Includes RN's

as usual  
 but not allowing  
 passage across an end.



Knot type  
 knotoids



~  
 ↑ No!



$$\langle \bigcirc \rangle = q + q^{-1}$$

$$\langle \curvearrowright \rangle = q + q^{-1}$$

Usual  $\langle \rangle$  poly for hermitian

$$\langle \cdot, \cdot \rangle = A \langle \cdot, \cdot \rangle + \bar{A}^{-1} \langle \cdot, \cdot \rangle$$

$$\langle OK \rangle = (-A^2 - \bar{A}^{-2}) \langle K \rangle$$

$$\langle \cdot, \cdot \rangle = 1$$

$\mathbb{R}^2 + \mathbb{R}^3$

$$f_K(A) = (-A^3)^{-\text{wr}(K)} \langle K \rangle$$

$$\langle \cdot, \cdot \rangle = A \langle \cdot, \cdot \rangle + \bar{A}^{-1} \langle \cdot, \cdot \rangle$$

$$\langle \cdot, \cdot \rangle = A \langle \cdot, \cdot \rangle + \bar{A}^{-1} \langle \cdot, \cdot \rangle$$

$$= (A + \bar{A}^{-1}) \langle \cdot, \cdot \rangle$$

$$= A(A + \bar{A}^{-1}) + \bar{A}^{-1}(-A^{-3})$$

$$= A^2 + 1 - A^{-4}$$

$$f_K = (-A^3)^{-2} \langle K \rangle = A^{-4} + A^{-6} - A^{-10}$$

$\Rightarrow K \not\cong K^*$  non trivial

Usual  $\langle \rangle$  poly for knotoids

$$\langle \nearrow \searrow \rangle = A \langle \underline{\quad} \rangle + A^{-1} \langle \searrow \searrow \rangle$$

$$\langle OK \rangle = (-A^2 - A^{-2}) \langle K \rangle$$

$$\langle \curvearrowright \rangle = 1$$

---

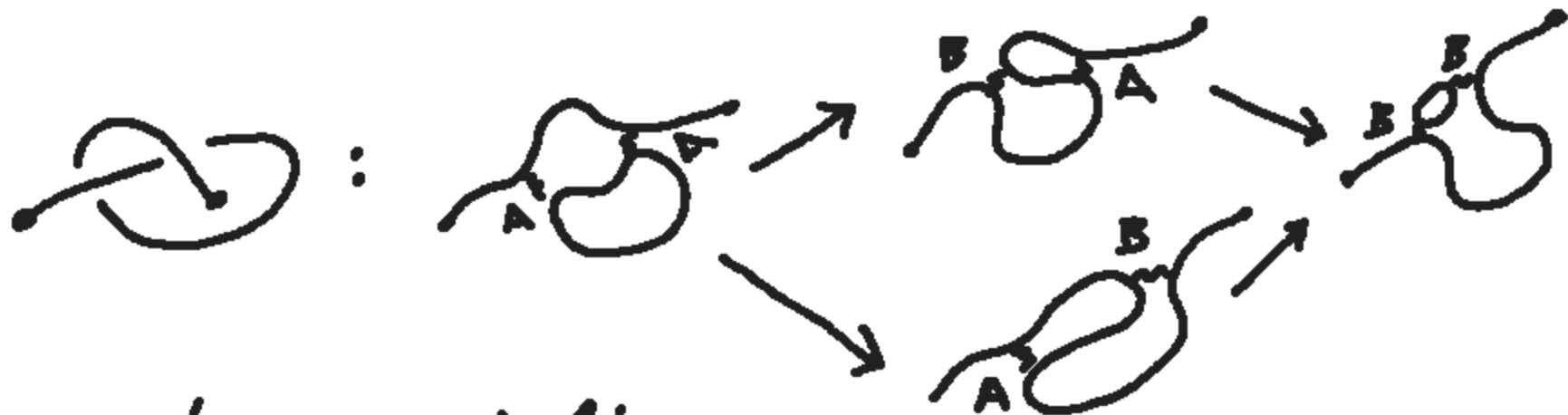
We can also take  $\langle K \rangle$  where

$K =$  virtual closure of the knotoid.

e.g.  $\langle \overline{\curvearrowright} \rangle = \langle \bigcirc \rangle$

$$\begin{aligned} &= A \langle \bigcirc \rangle + A^{-1} \langle \bigcirc \rangle = A(A + A^{-1}) + A^{-1}(-A^{-3}) \\ &= A^2 + 1 - A^{-4}. \end{aligned}$$

Exercise:  $\langle K \rangle$  (as defined above)  
 $= \langle K \rangle$  (as defined for virtual knots)

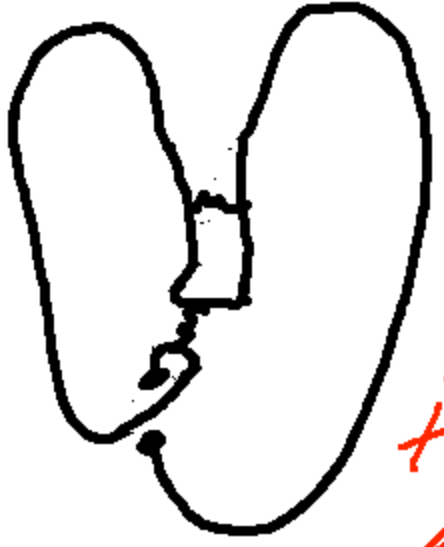
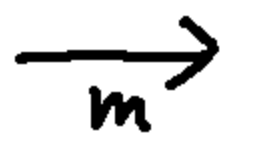
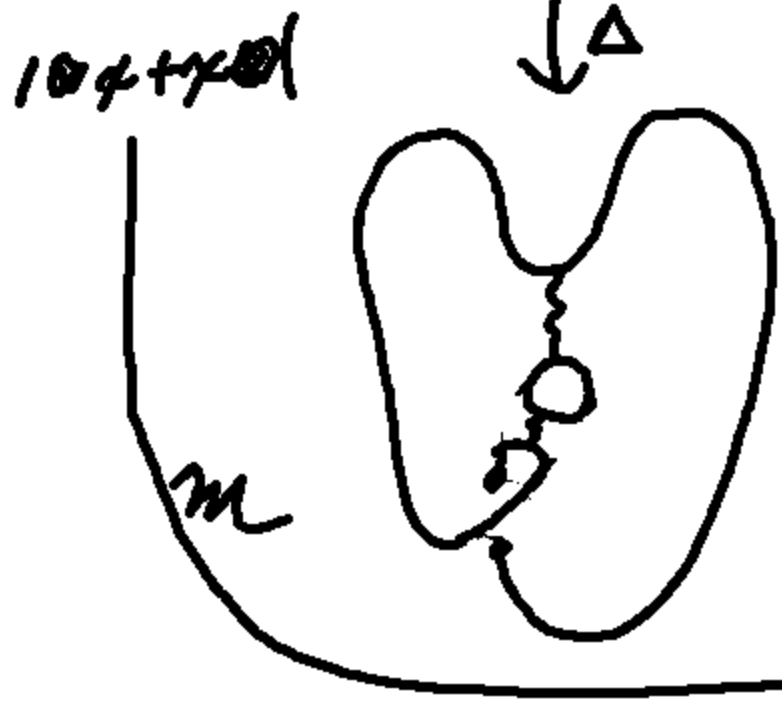
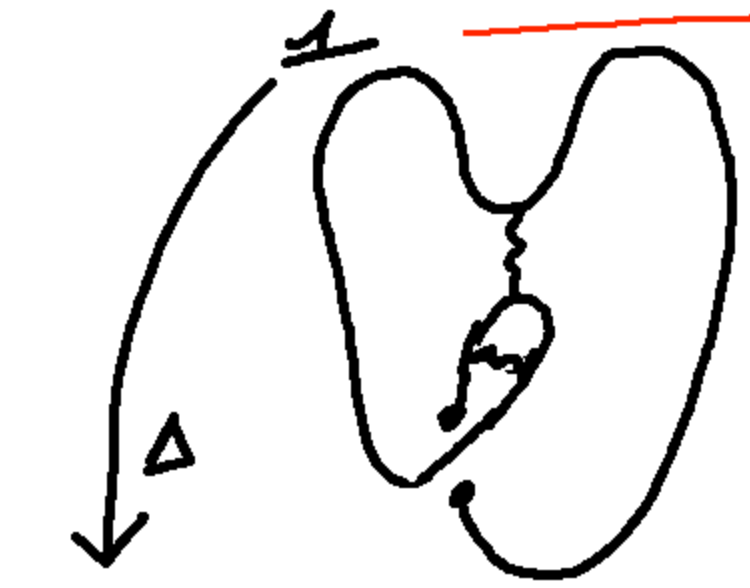


We can define Khovanov Homology for knotted exactly as we have defined Khovanov Homology for classical knots. For the long state  $\sim$  we associate the same module  $V = k[x]/(x^2)$  and generators  $\begin{matrix} + \\ - \end{matrix} \equiv \begin{matrix} \uparrow \\ \downarrow \end{matrix}$ .

WARNING!

$$\mathbb{Z} = \phi$$

$$\mathbb{Z} \rightarrow \mathbb{Z}$$



For Knotoids we have same problem with single component smoothing (See left) as for virtual knots. Thus we will discuss Khovanov Homology of Knotoids along with the virtual discussion!

$10\phi + 7\psi$

$2\psi$

Conjecture.  $\langle K \rangle$  detects the unknot.

---



Exercise  
compute  $\langle k \rangle$ .

$\langle k \rangle = \text{some } \pm \text{power of } A$

Conj  $\Rightarrow k \sim \bigcup$

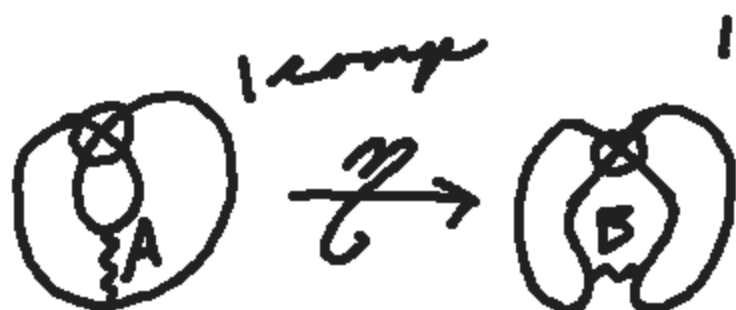
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Kho Homology for knots  
might detect the unknot.  
For classical knots this has been  
shown by Kronheimer and  
Mrowka.

---



# What about KhovH for virtuals?



single cycle.  
re-smoothing



non-orientable  
saddle pt.

$$\mathcal{A} = k[x]/(x^2)$$

Khovanov  
algebra.

$$\eta: \mathcal{A} \rightarrow \mathcal{A}, \quad m: \mathcal{A} \otimes \mathcal{A} \rightarrow \mathcal{A}$$

$$\Delta: \mathcal{A} \rightarrow \mathcal{A} \otimes \mathcal{A}$$

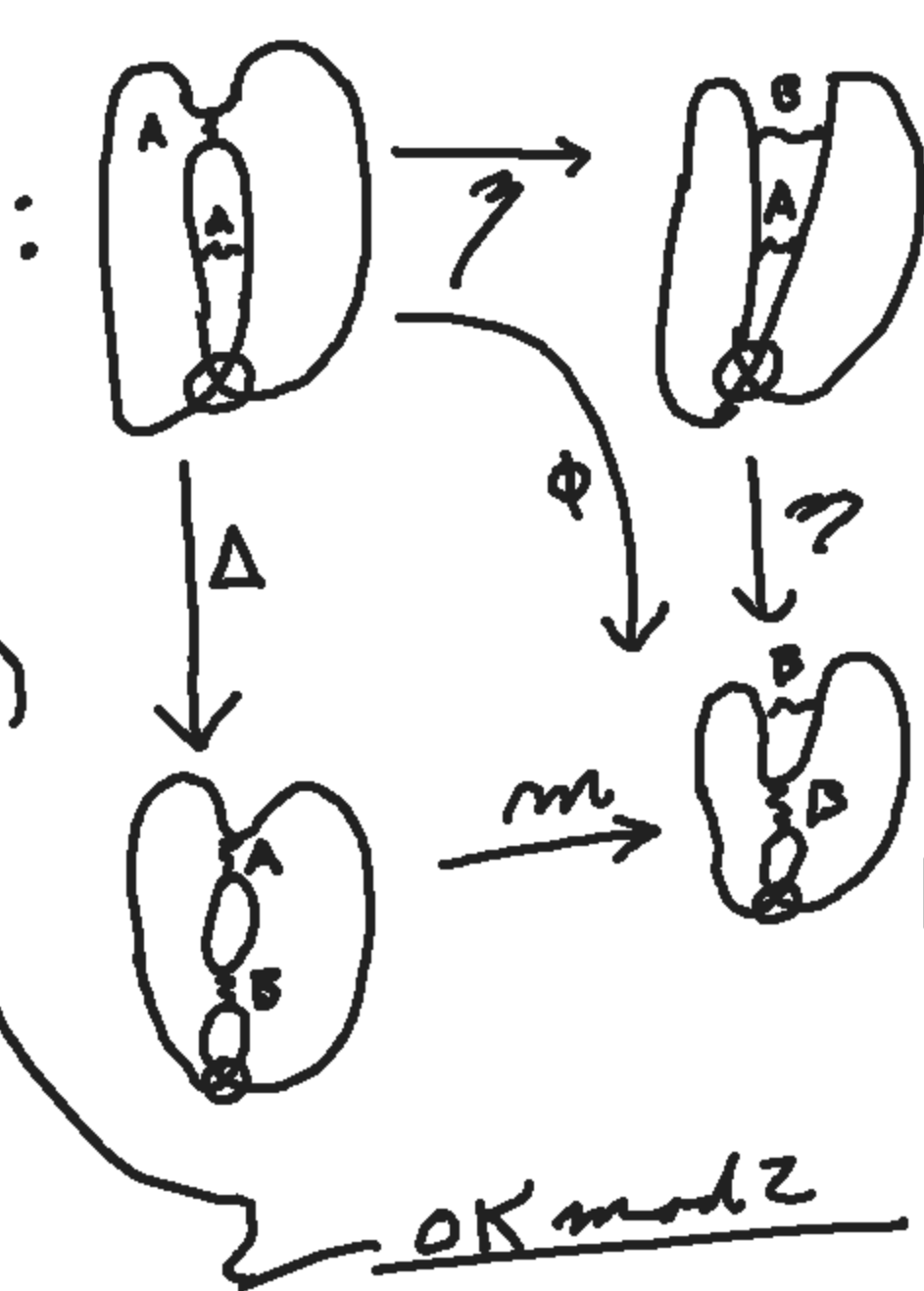
assume now

$$\eta = 0.$$



$$\begin{aligned}
 & m \circ \Delta(1) \\
 &= m(1 \otimes \gamma + \gamma \otimes 1) \\
 &= \gamma + \gamma \\
 &= \underline{\underline{2\gamma}}
 \end{aligned}$$

$$\begin{aligned}
 & m \circ \Delta(\gamma) \\
 &= m(\gamma \otimes \gamma) \\
 &= \gamma^2 = 0 \quad \checkmark
 \end{aligned}$$



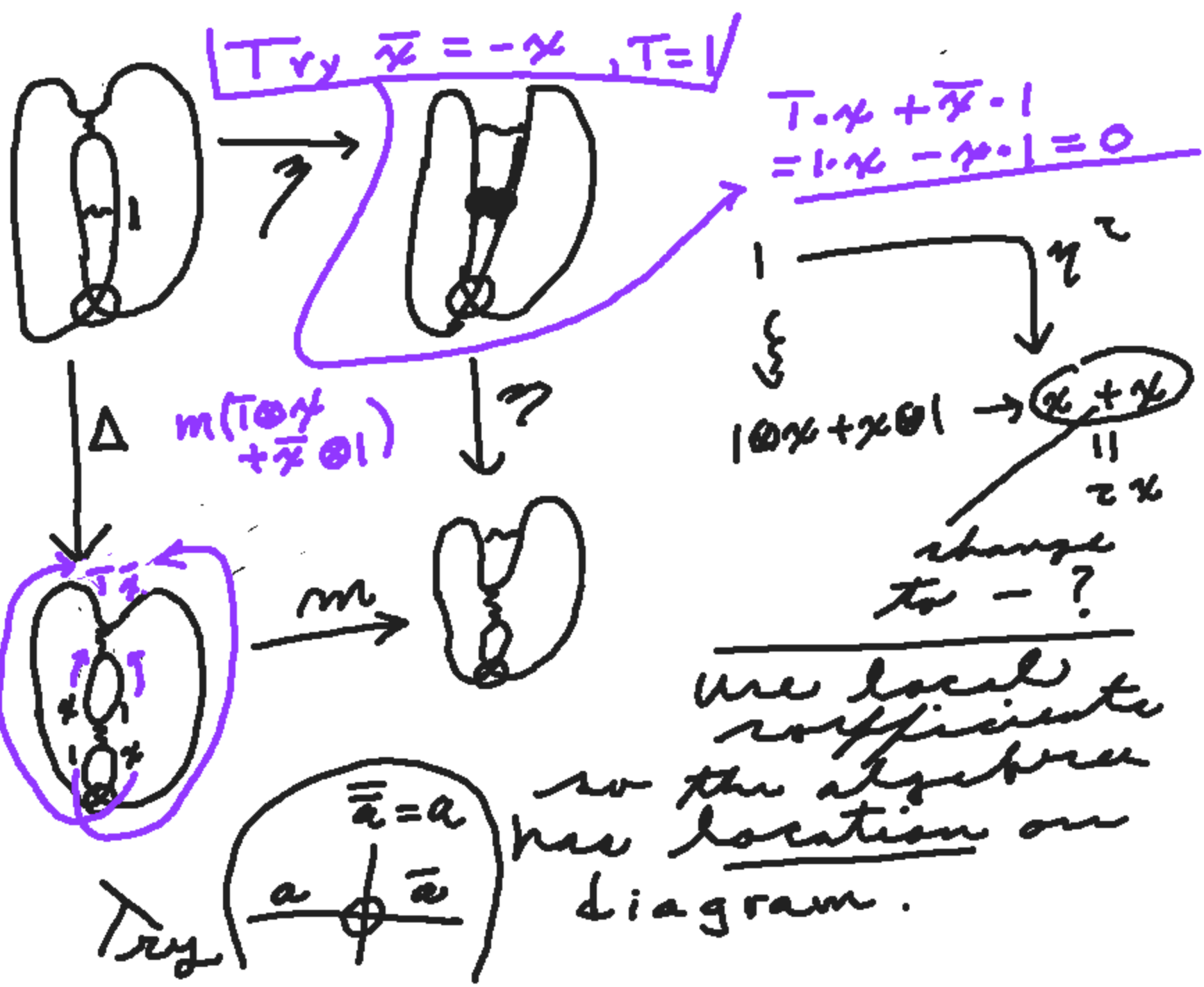
$$\gamma = \phi$$

Fact  
 $KhoH^*$   
 OK mod 2  
for virtuale.

Examples



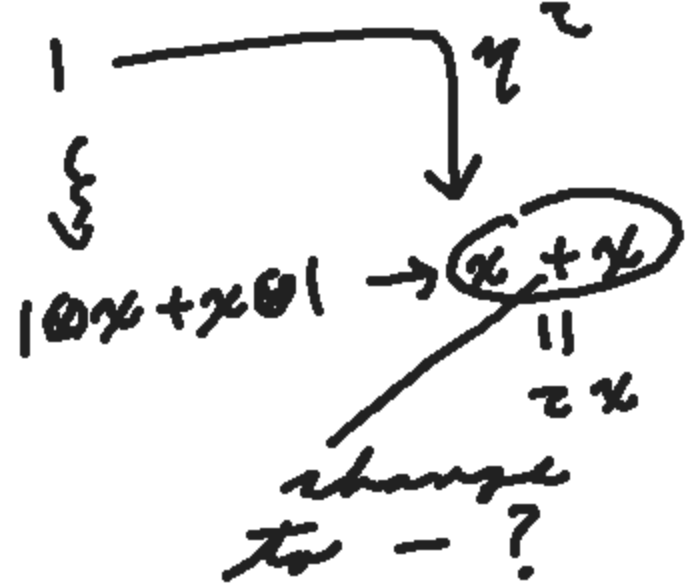
OK mod 2



$$Tr_y \bar{x} = -x, T=1$$

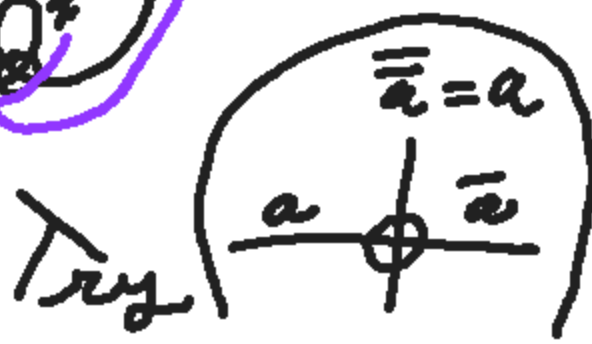
$$T \cdot x + \bar{x} \cdot 1 = 1 \cdot x - x \cdot 1 = 0$$

$$m(T \otimes x + \bar{x} \otimes 1)$$

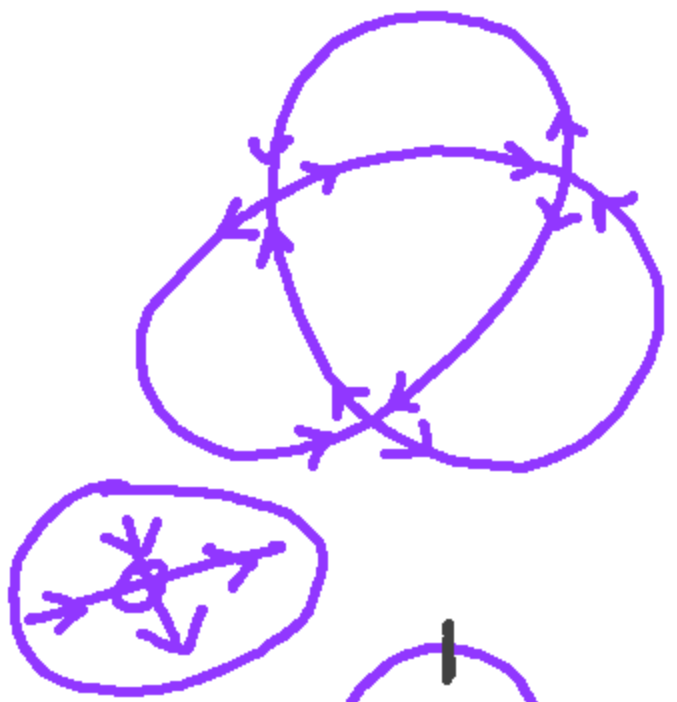


$x \cdot 1 + 1 \cdot x$

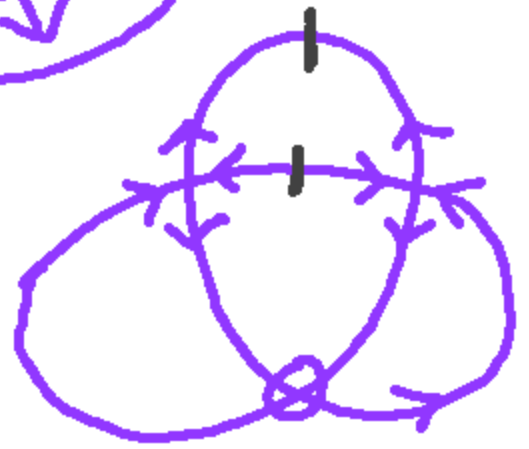
Use local coefficients  
so the algebra has location on diagram.



 source sink  
orientation



Can always deconstruct  
a directed diagram  
with a source sink  
orientation.  
Exercise!



It turns out  
that we can  
measure  
involutions  
across  
cut-points.

This  
will be  
the  
subject  
of the  
next  
lecture.