

Virtual quandle for links in lens spaces (Based on joint work with A. Cattabriga, 2019)

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 $G(L) = \langle x_1, x_2, x_3 \mid x_3^{-1}x_1x_3 = x_2, x_1^{-1}x_2x_1 = x_3, x_2^{-1}x_3x_2 = x_1 \rangle.$



Quandle of a link

Quandle Q is an algebraic system (Q, *) such that

- 1 x * x = x for all $x \in Q$.
- 2 The map $S_x : y \mapsto y * x$ is a bijection of Q.
- 3 (x*y)*z = (x*z)*(y*z) for all $x, y, z \in Q$.



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The quandle Q(L) can be found in the following way



Generators: labels on the arcs. Relations: x * y = z near all crossings.



Geometric definition of a quandle





Quandle is an almost complete invariant

Theorem

Let L_1, L_2 be two links in S^3 . Then $Q(L_1)$ and $Q(L_2)$ are isomorphic if and only if L_1, L_2 are weakly equivalent.



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- J. Pure Appl. Algebra, V. 23, N. 1, 1982, 37–65.



S. Matveev, Distributive groupoids in knot theory Mat. Sb. (N.S.), V. 119(161), N. 1(9), 1982, 78–88.







L. Kauffman, Virtual knot theory European J. Combin., V. 20, N. 7, 1999, 663–690.



Equivalent virtual links

Two virtual knot diagrams are called equivalent if one of these diagrams can be transformed to another one by a finite sequence of moves depicted below.





<u>Goussarov-Polyak-Viro, 2000</u>: Let L_1 , L_2 be two virtual link diagrams which have only classical crossings. If these link diagrams are equivalent as virtual diagrams, then they are equivalent as classical knot diagrams.



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→ $\widetilde{Q}(L)$





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Label the long arcs by x_1, x_2, \ldots, x_n . Then $\tilde{Q}(L)$ has Generators: labels on the long arcs. Relations: x * y = z near all crossings, where the labels are as on

 $\widetilde{Q}(L) = \langle x_1, x_2 \mid x_2 * x_1 = x_1, x_1 * x_1 = x_2 \rangle = \{x_1\}.$



Virtual quandle VQ is an algebraic system (Q, *, f) such that

- 1 (Q, *) is a quandle.
- 2 The map $x \mapsto f(x)$ is bijective.
- 3 f(x * y) = f(x) * f(y).



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Let p, q be coprime integers. $L(p,q) = B^3 / \sim$, where $x \sim f_3 \circ g_{p,q}(x)$.



L(p,q) can be obtained by a p/q rational surgery on the unknot in the 3-sphere S^3 .



Links in lens spaces

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S. Stevan, Torus knots in lens spaces and topological strings App. Henry Poincare, V 16, 2015, 1037, 1067

Ann. Henry Poincare, V. 16, 2015, 1937–1967.



Surgery link





Mixed link diagram





Punctured link diagram





Punctured link diagram





Band diagram





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Two band diagrams represent equivalent links in L(p, 1) if one of these diagrams can be transformed to another one by a finite sequence of moves depicted below.



Invariants

Let S be an arbitrary set. The map f from the set of all links to the set S is called S-valued knot invariant if for any two equivalent links L_1 , L_2 the values $f(L_1)$, $f(L_2)$ are the same.

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Let $\pi: S^3 \to L(p,q)$ be the universal cover map. Let f be an S-valued invariant for links in S^3 .

For a link L in L(p,q) denote by \tilde{f} the map given by $\tilde{f}(L) = f(\pi^{-1}(L))$ is an invariant for links in L(p,q).



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Manfredi, 2018: $Q_1(L) \simeq Q_2(L)$.









Label the arcs: Left by x_1, x_2, \ldots, x_n Right by y_1, y_2, \ldots, y_n Remaining by z_1, z_2, \ldots, z_m





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To each right point associate the number ε_i $\rightarrow | \ \varepsilon_i = 1$ $\leftarrow | \ \varepsilon_i = -1$



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▶ Generators: x₁, x₂,..., x_n, y₁, y₂,..., y_n, z₁, z₂,..., z_k;
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(ii) x * y = z, where x, y, z are as on z ∨ y





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 Inner relations: (i) identifications between some of x₁,..., x_n, y₁,..., y_n, z₁,..., z_k
 (ii) x * y = z, where x, y, z are as on
- Boundary relations: $f(x_i) = y_i$ for i = 1, ..., n $y_n^{\varepsilon_n} y_{n-1}^{\varepsilon_{n-1}} \dots y_1^{\varepsilon_1} \equiv 1;$



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- Splitting relations: $xf(x) \dots f^{p-1}(x) \equiv 1$ for all $x \in F(X)$ $f^p(x) = x$ for all $x \in VQ(K)$.



$$y_n^{\varepsilon_n} y_{n-1}^{\varepsilon_{n-1}} \dots y_1^{\varepsilon_1} \equiv 1$$

It means that for all $x \in Q$

$$x * (y_n^{\varepsilon_n} y_{n-1}^{\varepsilon_{n-1}} \dots y_1^{\varepsilon_1}) = x$$



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Here:

$$x *^{1} y = x * y$$

 $x *^{-1} y = S_{y}^{-1}(x)$, where $S_{x} : y \mapsto y * x$.



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Better than $Q(L) = Q_1(L) = Q_2(L)$. Is able to distinguish links with equivalent lifts. Easy computable from the diagram. Nice idea.









$$VQ(K) = \langle x_1, x_2, y_1, y_2 \mid x_1 = y_2, x_2^{x_1} = y_1,$$

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$$\begin{aligned} f^2(x) &= x^{f(x)}, \, xf(x) \equiv 1 \Rightarrow f^2(x) = x. \\ p \text{ is odd } \Rightarrow (f^2(x) = x, \, f^p(x) = x) \Rightarrow f(x) = x \end{aligned}$$



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